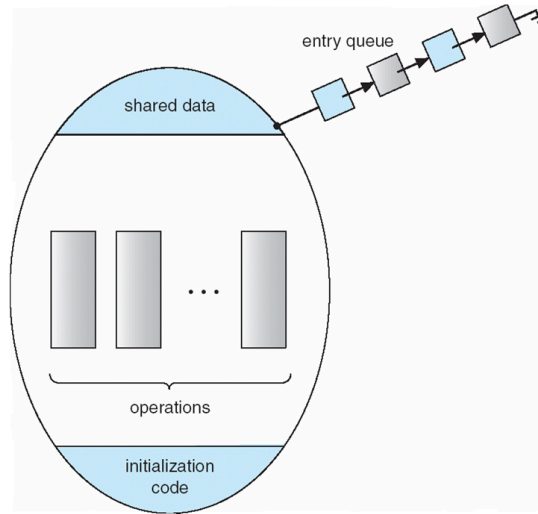


# Monitors



# Producer/Consumer with Java Monitors

```
class Queue {  
    private ...; // queue data  
  
    public synchronized void add(Object item) {  
        put item on queue;  
        this.notify(); // wake up waiting thread, aka Signal  
    }  
  
    public synchronized Object remove() {  
        while queue is empty {  
            this.wait(); // give up lock and sleep  
        }  
        remove and return item;  
    }  
}
```

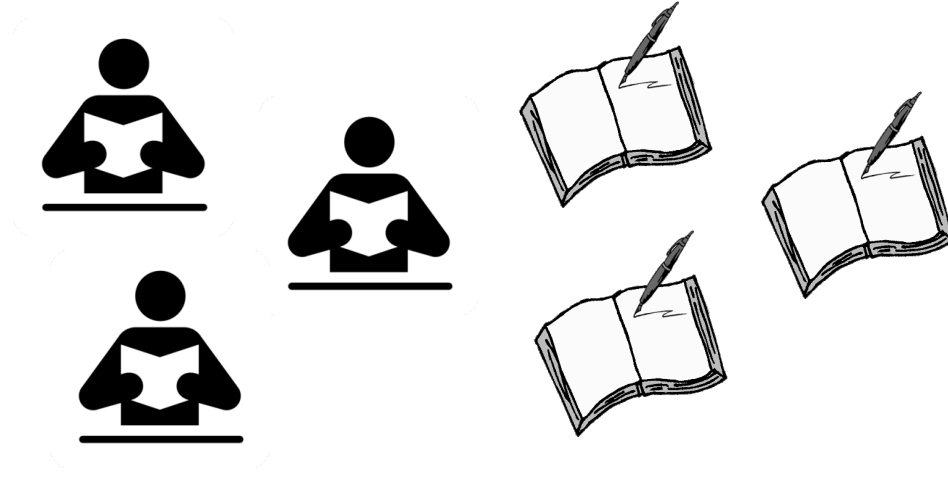
## (Pseudo) C++ Monitors

```
class Queue {  
public:  
    add();  
    remove();  
private:  
    Lock lock;  
    ConditionalVariable cv;  
    Queue data;  
}  
  
Queue::add(item) {  
    lock->acquire();  
  
    put item on queue;  
    cv->signal();  
  
    lock->release();  
}  
  
Queue::remove()  
    lock->acquire();  
  
    while queue is empty  
        cv->wait(lock); // release lock & sleep  
    remove item from queue;  
  
    lock->release();  
    return item;  
}
```

## Semaphore using a Montiors

```
Semaphore(initialVal) {  
    int counter = initialVal;  
    Lock lock;  
    ConditionVariable notZero;  
}  
  
Semaphore::Wait() {  
    lock.acquire();  
  
    while (counter == 0)  
        notZero.wait();  
    counter--;  
  
    lock.release();  
}  
  
Semaphore::Signal() {  
    lock.acquire();  
  
    counter++;  
    notZero.signal();  
  
    lock.release();  
}
```

## Readers/Writers Problem



## Readers/Writers with Semaphores

```
class ReadWrite {
public:
    void Read();
    void Write();
private:
    int readers = 0;
    Semaphore mutex = 1;
    Semaphore wrt = 1;
}
```

## Readers/Writers with Semaphores

```
class ReadWrite {
public:
    void Read();
    void Write();
private:
    int readers = 0;
    Semaphore mutex = 1;
    Semaphore wrt = 1;
}

ReadWrite::Write() {
    wrt.Wait();
    <perform write>
    wrt.Signal();
}
```

## Readers/Writers with Monitors

```
class ReadWrite {
public:
    void Read();
    void Write();
private:
    int readers = 0;
    Semaphore mutex = 1;
    Semaphore wrt = 1;
}

ReadWrite::Write() {
    wrt.Wait();
    <perform write>
    wrt.Signal();
}

ReadWrite::Read() {
    mutex.Wait();
    readers++;
    if (readers == 1)
        wrt.Wait();
    mutex.Signal();
    <perform read>
    mutex.Wait();
    readers--;
    if (readers == 0)
        wrt.Signal();
    mutex.Signal();
}
```

## Readers/Writers with Monitors

```
private int numReaders = 0;
private int numWriters = 0;

private synchronized void prepareRead() {
    while (numWriters > 0) wait();
    numReaders++;
}

private synchronized void doneRead() {
    numReaders--;
    if (numReaders == 0) notify();
}

public ... doRead() {
    // reads NOT synchronized
    prepareRead();
    <do the reading>
    doneRead();
}
```

## Readers/Writers with Monitors

```
private int numReaders = 0;
private int numWriters = 0;

private synchronized void prepareRead() {
    while (numWriters > 0) wait();
    numReaders++;
}

private synchronized void doneRead() {
    numReaders--;
    if (numReaders == 0) notify();
}

public ... doRead() {
    // reads NOT synchronized
    prepareRead();
    <do the reading>
    doneRead();
}

private void prepareWrite() {
    numWriters++;
    while (numReaders > 0) wait();
}

private void doneWrite() {
    numWriters--;
    notify();
}

public synchronized void doWrite (...) {
    // writes synchronized
    prepareWrite();
    <do the writing>
    doneWrite();
}
```