Finding collinear points

The problem: Given a set of n points in the plane, determine if there exist three points that are collinear.

We'll assume that we can check whether any three given points are collinear in O(1) time. We'll come back with details on how to do this next week.

Brute force

Algorithm 1 (brute force)

- for all distinct triplets of points p_i, p_j, p_k : if collinear return true
- (if you get here) return false

- Argue that the algorithm is correct (can it miss any triplets?).
- What is the (worst-case) running time?
- How much space does it use?

Via sorting

Algorithm 2

- initialize array L = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (slope, intercept) and add it to an array L
- sort array L by (slope, intercept)
- traverse L and if you find any 3 consecutive identical (s,i) \rightarrow collinear

- Argue that the algorithm is correct.
- What is the (worst-case) running time?
- How much space does it use?

With a binary search tree

Algorithm 3

- initialize BBST = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (s, i)
 - insert (s,i) in BBST; if when inserting you find that (s,i) is already in the tree, you got three collinear points and return true
- (if you ever get here) return false

- Argue that the algorithm is correct.
- What is the (worst-case) running time?
- How much space does it use?
- How does it compare to Algorithm 2?

With hashing

Algorithm 4

- initialize HashTable = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (s, i)
 - insert (s,i) in HashTable; if when inserting you find that (s,i) is already in the HT, you got three collinear points and return true
- (if you ever get here) return false

- Argue that the algorithm is correc.
- What is the (worst-case) running time?
- How much space does it use?
- Hoes does it compare to Algorithm 3?
- Under what assumption on the input is Algorithm 4 faster than Algorithm 3?

A different way to sort

Algorithm 5

- for every point p_i
 - set array L = empty
 - for every point p_j (with $p_j! = p_i$)
 - * compute slope of p_j wrt to p_i and add it to array L
 - sort L
 - traverse L and if you find two consecutive points that have same slope, they are collinear with p_i so return true
- (if you get here) return false

- Argue that the algorithm is correct (can it miss any triplets?).
- What is the (worst-case) running time?
- How much space does it use?